

PalArch's Journal of Archaeology
of Egypt / Egyptology

PHYSICAL PLANNING FOR TRANSPORTATION IN SMART CITIES FOR ACHIEVING SUSTAINABLE DEVELOPMENT STRATEGY

Samera Al-Addal

Faculty of Physical Planning, University of Kufa, Najaf, Iraq.

**Samera Al-Addal , Physical Planning For Transportation In Smart Cities For
Achieving Sustainable Development Strategy , Palarch's Journal Of Archaeology Of
Egypt/Egyptology 17(6). ISSN 1567-214x.**

**Keywords: Physical Planning, Transportation in Smart Cities, Sustainable
Development strategy, regional planning.**

Abstract:

Intelligent Transportation Systems (ITS) are ingrained in our daily lives and represent the transportation industry's future. They enable us to address some of our society's most pressing issues, such as traffic safety and pollution reduction. Transport in the future will be routed autonomously. It will not contribute to pollution in the atmosphere and will provide drivers with more comfort. There is also an infrastructure component. Vehicles and infrastructure will communicate data to reduce gridlock, improve the flexibility of crossings, and prevent accidents. There are multiple types of computer networks that provide communication between the many components of an ITS, such as information and communication technology embedded in cars and transportation infrastructure. These technologies will transform how we travel today. These programs let you share and gather essential information between vehicles and between infrastructure and vehicles to assist drivers in traveling safely and comfortably. This work aims to offer the result in real time and with a high degree of reliability for vehicle networks.

1. Introduction :

Traffic management and user information measures associated with "intelligent" transport systems are becoming increasingly crucial in transport policy: they are presumed to be less costly in solving congestion problems and reducing traffic consumption. Energy and the related greenhouse gas emissions; are oriented towards the user and the quality of service. As such, they facilitate an intermodal approach. They play more particularly on the reliability and safety of transport. However, the measures to manage traffic and information from users present high costs. Their cost-benefit

balance deserves to be evaluated in the same way as other transport projects and policies. It is indeed desirable to compare these projects with those which preferentially play on the capacity of the networks.

Additionally, the ability to pick the most successful dynamic traffic control projects for the community is desirable. It is essential to equip decision-makers and managers with tools for evaluating ITS projects To support intelligent transport systems. All stakeholders currently recognize the lack of evaluation as an obstacle to the deployment of ITS. Governments in Europe, the United States, and Japan have invested heavily to improve intelligent transportation systems. Consequently, many research and development projects have been implemented to enhance the performance of intelligent transportation systems. These projects have been particularly successful in standardizing some communication and processing technologies assigned to intelligent transportation systems and increasing the reliability to meet the unique challenges presented by these systems. These projects also led to the birth of the smart car and its increased performance, which combined the ability to discover the state of the environment with the ability to communicate information instantly. Intelligent transportation systems have relied on detectors and cameras along the road network and central monitoring stations to discover traffic. A new generation of intelligent transportation systems has emerged based on connected vehicles and V2V and V2I communications. These systems are then referred to as VANETs, focus primarily on connected vehicles and the infrastructure connected by RSU and Road Side Unit. However, VANETs have many limitations, among them: the need for a dedicated communications infrastructure, lack of centralized management of traffic data, and difficulty integrating new applications and services to manage traffic (Bonnefoi, Bellotti, Schendzielorz, & Visintainer, 2007).

2. What is the ITS, and how it works?

Intelligent transport systems are the systems that allow processing, analysis, and communication of information related to transportation systems. It is called brilliant because it is based on functions related to intelligence, such as information processing, communication, memory, and adaptation to imposed conditions. In Europe, all these technologies based on intelligent transport systems are grouped under the term transport telematics. New technologies in transportation have greatly accelerated the development of intelligent transportation systems in recent years. These systems are integrated (or in the process of integration) in all modes of transport. Vehicles, users, or infrastructure can be equipped with it. Its main task then is to assist in decision-making by transmission network operators and other users. These processes are often implemented in real-time, and they improve everyone's living conditions. The use of intelligent transportation systems is also part of the desire for sustainable development. Indeed, intelligent transportation systems lead to better-coordinated road use through the use of data. Therefore, the information is necessary to know the network's current state or plan its use.

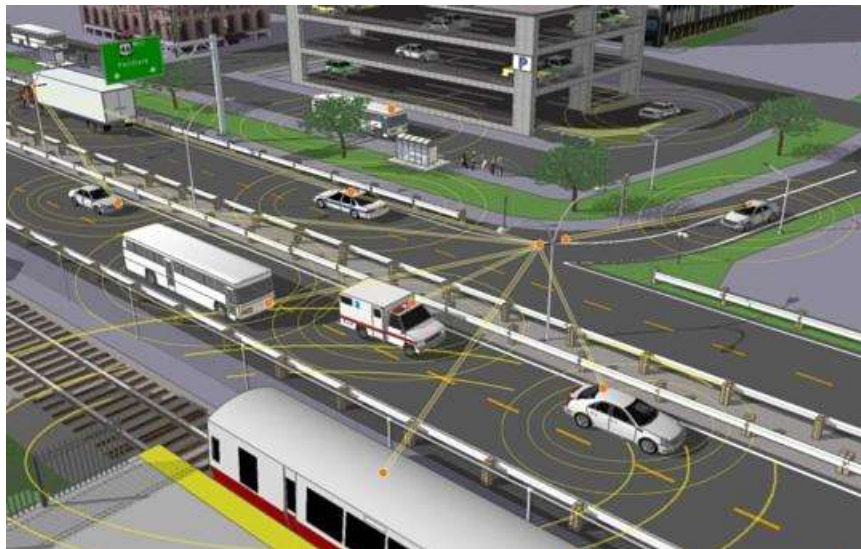


Figure 1. Applications of Intelligent Transport System

Intelligent transportation systems aim to address social issues related to transportation use. It is rooted in the goal of enhancing systems for consumers, drivers, and administrators. Thus, intelligent mobility networks are mainly used to control road traffic congestion and to create emerging information technology for cars.

Under this last category, we have modeling, networking networks, and real-time monitoring. Thus, Intelligent transportation systems allow the transportation system to operate more efficiently through a variety of means. It is about saving time, lowering prices—mostly on energy consumption—and efficiency, and saving lives. World wide, intelligent transportation networks are in use and are increasingly being improved. We often use Intelligent Transportation Systems (GPS, ADAS...) without realizing it in the transportation industry or as customers (GPS, ADAS...). The adoption of these new transportation schemes is welcomed for various reasons, including reducing the risk of human error and thereby increasing overall protection. These devices are ubiquitous in our culture, and their presence in the field of transportation is only average. For instance, cruise control and collision detection are often used in modern automobile models. Today, systems that enhance driver safety referred to as cooperative vehicle infrastructure are still being developed. The objective is to incorporate them into future generations of cars. Another aim of intelligent transportation infrastructure is to reduce automotive emissions. It will necessitate improved pollution control and the use of low-fuel engines. However, the environmental problem is not limited to automobiles. To control air quality, infrastructure has been developed. Its objectives are to identify and deter emissions and incorporate policies to mitigate the risks associated with air pollution. Finally, eliminating congestion entails substituting public transit for private automobiles. In major cities, public transit is commonly used. Indeed, it facilitates traffic management and promotes environmental stewardship. Therefore, it is essential to enhance these modes of transportation in terms of travel time, punctuality, and efficiency. To do this, it is fascinating to collect data in real-time from a variety of stations. There is an answer to this problem. We need to construct a fleet of wholly automated cars and provide them to the public in the same manner.

3. Technology of Cyber-cars:

The term "Intelligent Transportation Systems" refers to a set of innovations to enhance the quality of various modes of transportation in the modern era. Its progress is ongoing and fast, with the ultimate goal

of complete automation of induced systems. This result has already been designated and is currently being developed: It is for electric automobiles. The development of the electric car originated in Europe in the early 1990s. In 1997, the Netherlands developed the first electronic vehicle-like system to transport passengers via Schiphol Airport. To put it more precisely, electric cars are road vehicles that run entirely independently of human intervention and need no maintenance. As a result, certain vehicles do not need a pilot. People and products are to be moved along well-defined road networks via the ASDs. This traffic technology is meant to adapt to various traffic circumstances (inclement weather, gridlock, road obstructions, etc.) (Milanés, Marouf, Pérez, González, & Nashashibi, 2014). However, for autonomous vehicles, many stages of automation can be defined:

Level 0: Traditional car, without an auto character.

Level 1: aids the driver in driving but does not propel him (parking assist, cruise control, for example). Level 2: Automation is partial, but the driver must always control the drive (the device will, for example, navigate traffic jams).

Level 3: Automation is successful where predefined conditions are met. As a result, the driver can be obliged to reclaim manual control of his car on occasion (e.g., automatic highway system).

Level 4: High Automation, in which the car runs autonomously in a wide variety of complex environments (including urban areas), but the driver must remain present and technically controllable.

Level 5: Automation is complete, and the vehicle can run autonomously under all environments. A driver is not needed (Cui & Sabaliauskaite, 2017).

The car is classified as a Level 5 vehicle under this metric because it does not need a driver. However, in the current study, such vehicles operate only for particular purposes, such as transporting goods within a specific metropolitan region or transportation of goods within an industrial field.

4. Categories of ITS:

The world's roads are currently home to millions of cars, and their number continues to grow. As a result, improving traffic quality, reducing pollution, and mitigating the harm caused by collisions have become significant problems in cities. During the last decade, this has dramatically increased due to the implementation of intelligent transportation networks and information and communication technology.

Vehicles systems can communicate with other vehicles in an intelligent transportation system through Vehicle-to-Vehicle Communication (V2V) or Infrastructure-to-Vehicle Communication (V2I) technologies. There are two primary categories of ITS applications: protection and reliability of traffic flow (A, B) (Racoceanu, 2006):

A. Road, safety, applications:

Road safety applications seek to reduce the risk of automobile crashes and the harm incurred by unavoidable collisions. These implementations need dedicated hardware that is both reliable and timely and dependable connections. These solutions range from mutual recognition, such as progress monitoring, lane departure alert, and speed management, to emergency applications, such as danger identification and adverse weather conditions.

B. Applications of Traffic Efficiency:

The primary objective of traffic efficiency is to increase traffic flow by minimizing travel time and congestion. Additionally, economic and environmental gains can be realized. These applications provide users with traffic information, which is typically broadcast through infrastructures.

Managing equipment used to carry hazardous materials. Although these demands do not have stringent reliability or timeliness, their efficiency degrades with increasing delay and package failure (OUDJEDI DAMERDJI & REMACI, 2020).

5. Research Projects on cooperative intelligent transport systems (C-STI):

Autonomous vehicle deployment can depend on developing connected infrastructures: it is necessary to ensure the homogeneity of investments in the different regions to avoid the presence of "white areas" of mobility. To enhance the deployment of autonomous vehicles, the goal is to be aware of their environment and know the traffic conditions on the road dynamically (in real-time) without requiring huge investments. C-STI, also known as cooperative intelligent transport systems (C-ITS), is an alliance of transportation systems, cars, and other infrastructure components that encourages information sharing and communication. Road safety, road personnel safety, traffic management and improvement, road information, and infrastructure management. The Cerema Center for Studies and Experience in Risk, Environment, Mobility, and Planning in France contributes to several research projects related to intelligent transport systems, including:

SCOOP: a French pilot project supported by the European Commission to deploy collaborative intelligent transport systems (without autonomous driving) to develop use cases aimed at improving the operating efficiency of road networks. Thus, boarding gear and information exchange within vehicles were deployed.

In continuation of Scoop, this collaborative ITS deployment project has enabled the coordinated development of use cases and user services on a European scale. The C-ROADS platform brings together 16 European countries.

INDID: This French research project funded by the European Commission has launched four and a half years ago, with 24 partners. It focuses on the role of new technologies and use cases related to autonomous vehicles, infrastructure improvement, and advanced security solutions in particular.

FENIX: Project to develop and deploy a digital information system for logistical transport along several European corridors. It is coordinated by ERTICO, the European network that brings together stakeholders in Intelligent Transport Systems (ITS) and brings together 26 partners from 12 European countries, including 6 French partners.

DENSE (adverse weather environmental sensing system) This European research project, implemented in partnership with research centers, automobile manufacturers, equipment manufacturers, and start-ups, aims to develop sensors for intelligent vehicles capable of operating in severe weather conditions.

6. The contribution of intelligent transportation to sustainable development:

Since the development of intelligent cars offers new markets and provides a wealth of economic benefits, we must point out that it has happened in the past, and we see that it'll be the case again in the future. However, we will see that full automation of vehicles can cause some technical and legal issues, especially for the responsible agent in the event of an accident.

7. The contribution of intelligent transportation to economic development:

The spread of intelligent cars is leading to a change in the economic and legal view of traffic. Let's start by detailing these changes and their consequences from a financial point of view. The study sought to estimate the potential benefits envisioned in 2030 from creating and developing self-driving cars. According to the report by KPMG France (the French auditing and accounting firm), the profit will be 51 billion pounds or 70 billion euros. Lack of communication and sharing of information is one of the costliest factors of all transportation systems. This is why technologies such as the V2V (Vehicle to Vehicle) system are applied. It allows the transmission of information between vehicles, especially about traffic conditions and potential disturbances. The direct consequences are reduced traffic congestion and travel time, smoother traffic, reduced gas emissions, and reduced fuel consumption. In addition, all of these results have a positive impact on the environment. From a safety point of view, the number of accidents can be significantly reduced. Human error is the source of 90% of road accidents. Although driver assistance systems such as collision avoidance radar have already reduced the number of casualties, the number of traffic accident victims each year is still very high. According to a study by KPMG, electronic cars could prevent 30,000 hospitalizations per year in France and save 4 billion euros (Pavel, Vignolles, & Lallement, 2018). The introduction of self-driving vehicles also has other economic implications, such as job creation. Indeed, it is necessary to develop new sectors or new businesses. It is about a new market that can expect massive expansion in light of the demand for these products in our society. All production levels are involved: from engineering jobs to product development and improvement, to technicians and contractors to manufacture vehicles. We can also enjoy imagining the changes that the full implementation of autonomous vehicles could bring to our society. Using a compact car or larger vehicles will change all of our current transportation. As urban vehicle fleets develop, the personal car model disappears, at least in cities.

8. ITS CYBER-SECURITY CHALLENGES:

A. Cyber-attacks in ITS:

The proliferation of electronic control units (ECUs) has introduced new security vulnerabilities. Previously published works demonstrated how to compromise a car's internal network, including safety-critical components such as the brakes and engine. Builders are adaptable and do not want to spend vast sums of money in defense without a return on their investment. Recent exploits have shown that the protection systems offered by automobile manufacturers are rudimentary and insufficient. One of the primary reasons for dismissing these attacks is that they are scarce compared to the vast number of unhacked vehicles. According to some analysts, the episode is not worth the money spent on the cars. On the other hand, others argue that hackers' motivations are not only financial; they can be political or aggressive as well (Mohamed, Boulmakoul, & Karim, 2017).

B. Cyber security in ITS:

The following fundamental concepts denote cybersecurity specifications:

Confidentiality is the property of knowledge being protected from entities, processes, or persons.

Data integrity ensures the consistency of data from the point of origin to the end of the destination.

Authentication is the capability of determining if the parties to a contract are who they appear to be.

Availability: The property that makes knowledge available at all times when it is needed.

The term "**non-repudiation**" refers to the fact that one of the contracting parties cannot dispute the validity of his signature on the paper (Djakboub, 2017).

9. A Legal Aspect of intelligent transportation

To be legally purchased, self-driving vehicles will need to meet stringent European legislation that mandates the driver to be in charge of the car at all times. To place internet-connected automobiles in their rightful place in traffic, we must alter the law, but we must worry about specific other difficulties. One of the first things that have to be addressed is standardization and certification. To prevent legal loopholes, differing levels of automation in cars would necessitate the development of new regulations to handle each. It will be required to verify each of these levels using other tests and criteria and the ones indicated previously. This will enable each vehicle to be allocated into a class defined by the features of the car and the other vehicle classes in the same category. How do these laws identify themselves? As the first step, it is critical to determine what is considered safe driving for electronic automobiles. As a result, self-driving automobiles are tested. Currently, it is not authorized to have vehicles on the roadway, but tests of self-driving cars are allowed. To properly ensure the safety of everyone involved, the driver must be present, accept responsibility, and assure the safety of those traveling with him. To be eligible for insurance, the firm must seek clearance from the relevant government, as these examinations occur in other countries or regions. As a result, it is strongly recommended that a code of conduct and liability for motor vehicles be put in place. In addition to rules that electronic automobiles must follow during testing, this code also includes restrictions that vehicle makers must observe. This blog contains three major components. To be qualified to operate the self-driving car, the driver must be able to manage the vehicle at all times, be aware of the potential risks, and thoroughly schooled in the new technology. If the car is in operation, we must record driving data at all times to investigate and identify whether the vehicle is powered by automated or manual driving in the case of an accident. The final step is to test the technology and car in a closed circuit to authorize its implementation on the public road. Concerns over who would be liable in the case of an accident involving electronic automobiles are far from resolved. To what insurance policies would these automobiles be subject? Is the manufacturer or the driver (passive at the time) accountable to justice if an accident results in death? What is the use of a driver's license if they are not driving? Before introducing electronic automobiles into our metropolitan areas, all of these legislative and liability difficulties must be handled.

10. Future Developments:

The popularization of cybercars is not for tomorrow. However, many experiments were conducted with autonomous systems in France and around the world under everyday conditions. All tests went well, without incident (every time a human driver was in the car, the feet on the pedals were ready to step). So, it is natural to ask: Why aren't self-driving cars about to enter the market? The goal of the self-driving vehicle is to achieve a wholly autonomous and communications system. And it is precisely this part, the touch, that has yet to be developed. Imagine all the errors that can accumulate around calculations and estimates made on a long journey, becoming disastrous. Whereas having a fully cooperating network would make the trip more confident for the user. Some cars developed by INDID can detect signs, traffic lights, and pedestrian crossings. But what if the recognition algorithms fail or trees or other obstacles hide the mark? An accident can result from this lack of information. This is why many means are currently being deployed to improve and create communication systems between vehicles (V2V) and between infrastructure and vehicles (I2V) to increase the amount of information available again and again. Imagine, for example, in a city, all cars are communicating with each other. This means that each vehicle will share its location, speed, and destination with others. This will allow all vehicles to better cope with the congestion that all these journeys can generate together. Add to this traffic lights, signs, and pedestrian crossings that communicate with cars, giving information about their condition and the rules that apply (correct priority, presence of pedestrians, etc.). Building these infrastructures is the real challenge of tomorrow. The creation of connected structures should be a Smart City model, along-term solution, and thus it should be able to adapt to all processes of urban redevelopment (Galoul, 2015).

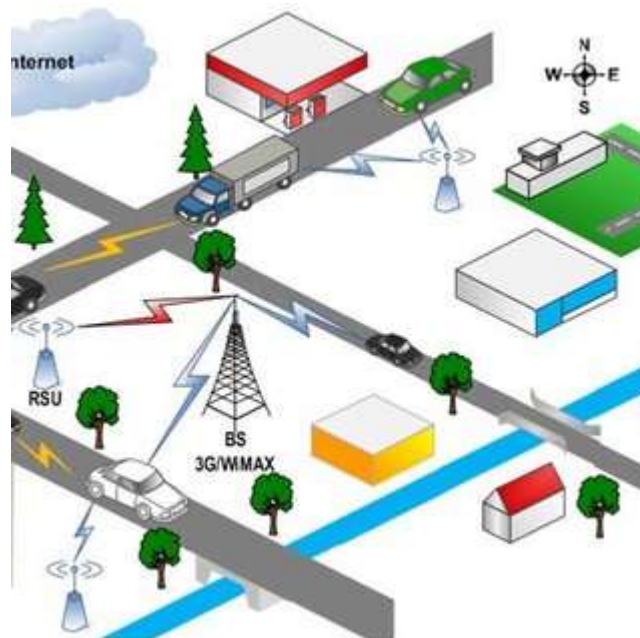


Figure2. Modeling of a V2V and I2V system

All this communication, which is being developed, will make it possible to bridge this information gap, making it possible to create safer and more adaptive transmission systems thanks to the constant flow of data being communicated. As in Melbourne (2006), some communications infrastructure had already emerged where an entire section of the highway detected traffic

conditions as well as speeding violations and sent this information back to a central center that processed it. But we realize that this communication is insufficient. We must publish this information (previously processed) to all vehicles using this road without being affected by other signals emitted by cars, mobile devices, etc. Even if some ideas are raised, many tests must be conducted, and high costs are incurred considering the feasibility of such an exchange of data. This is why all these issues represent the challenges of tomorrow for all engineers and researchers working in the field of intelligent transport systems, telecommunications, and data transmission. While awaiting the development and generalization of these communication infrastructures, the search for autonomous cars continues to provide a particular service without leaving any choice to chance.

Conclusions:

In the conclusion of our study of sustainable development of intelligent transportation, we conclude that smart transportation works to achieve several economic, social, and environmental goals. It will result in fewer accidents and less severity, and less traffic congestion. It also improves and encourages public transport services, reduces pollution resulting from emissions left by vehicles, and grants large margins for safety and security utilizing vehicle control and safety systems. It will lead to controlling spending on road construction and maintenance. In addition, information systems help road users reduce lost time in congestion, thus gaining more control and controlling vehicles and reducing accidents resulting from the car, human factor, or the environment. Despite their relevance in numerous modes of transportation, these systems are not included in the future projects on which scientific study is focused.

References:

- 1) Bonnefoi, F., Bellotti, F., Schendzielorz, T., & Visintainer, F. (2007). Specifying applications for infrastructure-based co-operative road-safety. Paper presented at the 14th World Congress on Intelligent Transport Systems.
- 2) Cui, J., & Sabaliauskaite, G. (2017). On the alignment of safety and security for autonomous vehicles. IARIA Cyber.
- 3) Djakboub, A. (2017). Application mobile de télésurveillance et alarme dans les villes intelligentes. FACULTE: Mathématiques et informatique-UNIVERSITE MOHAMED BOUDIAF-M'SILA,
- 4) Galoul, A. (2015). Les villes intelligentes: l'open data contribue-t-il à leur développement. Louvain School of Management, Université catholique de Louvain, Prom.: Belleflamme, Paul.
- 5) Hole, Y., & Snehal, P. & Bhaskar, M. (2018). Service marketing and quality strategies. Periodicals of engineering and natural sciences, 6(1), 182-196.
- 6) Hole Y., Hole S.P., & Wagh. V. (2019). Omnichannel retailing: an opportunity and challenges in the Indian market. Journal of Physics: Conference Series, 1362 (2019), 1-12.
- 7) Milanés, V., Marouf, M., Pérez, J., González, D., & Nashashibi, F. (2014). Low-speed cooperative car-following fuzzy controller for cybernetic transport systems. Paper presented at the 17th International IEEE Conference on Intelligent Transportation Systems (ITSC).
- 8) Mohamed, N., Boulmakoul, A., & Karim, L. (2017). 4ème édition de la Journée Doctorale des Sciences de Marrakech, Maroc.
- 9) Once, S., & Almogtome, A. (2014). The relationship between Hofstede's national cultural values and corporate environmental disclosure: an international perspective. Research Journal of Business and Management, 1(3), 279-304.
- 10) Pavel, I., Vignolles, D., & Lallement, G. (2018). Les enjeux économiques et industriels du

- véhicule connecté et automatisé. Paper presented at the Annales des Mines-Realites industrielles.
- 11) Racoceanu, D. (2006). Contribution à la surveillance des Systèmes de Production en utilisant les Techniques de l'Intelligence Artificielle. Habilitation à diriger des recherches, Université de FRANCHECOMTÉ de Besançon, France.
 - 12) REMACI, C., & OUDJEDIDAMERDJI, D. (2020). Applications de la technologie LPWAN dans les systèmes de transport intelligent.
 - 13) Zantalis, F., Koulouras, G., Karabetsos, S., & Kandris, D. (2019). A review of machine learning and IoT in smart transportation. Future Internet, 11(4), 94.